

A Framework for Universality in Physics, Computer Science, and Beyond

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References

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- [La69] F. W. Lawvere,
Diagonal arguments and cartesian closed categories.
Lecture Notes in Mathematics 92:134-145 (1969).
- [Pa18] D. Pavlovic and M. Yahia,
Monoidal computer III: A coalgebraic view of computability and complexity.
International Workshop on Coalgebraic Methods in Computer Science 167-189 (2018).
- [Fr22] T. Fritz, F. Gadducci, D. Trotta, and A. Corradini,
Lax completeness for gs-monoidal categories.
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Motivation

Motivating examples

Primary:

- ▷ universal Turing machines
- ▷ universal spin models [De16]

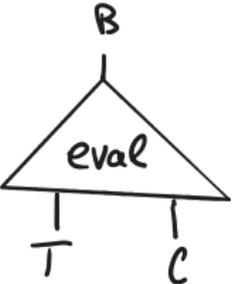
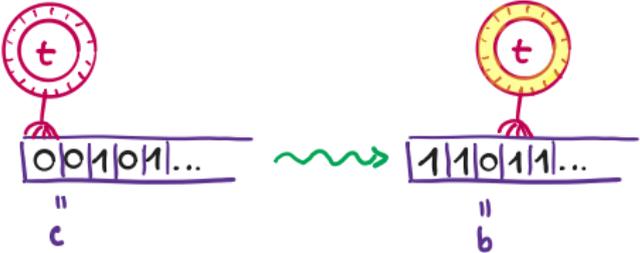
Others:

- ▷ NP-completeness
- ▷ dense subsets
- ▷ universal approximation by neural networks
- ▷ generating sets (universal gate set, ...)
- ▷ universal graphs
- ▷ xenobots and chemputers
- ▷ universal explanations (emergent properties) and universals in metaphysics

Goals of the framework

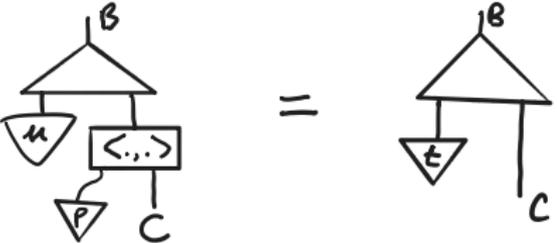
- ▷ Unified language
- ▷ Examples of universality
- ▷ Knowledge-organization
- ▷ General theory of universality
 - ▷ trivial vs. non-trivial universality
 - ▷ necessary conditions for universality
 - ▷ Fixed-point theorem + relation to undecidability

Universal Turing machine



∇^T_u is universal $\approx u$ can emulate any $t \in T$:

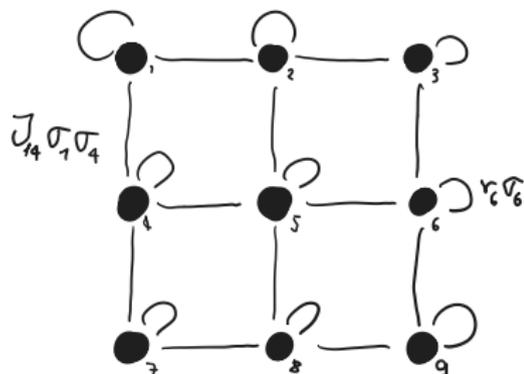
$\exists P = [001111]$:



Spin system

- ▷ Spin d.o.f. Σ for each vertex
- ▷ A hypergraph, edges \sim local interactions
- ▷ Hamiltonian $\Sigma^V \rightarrow \mathbb{R}$ as a sum of local coupling terms

2D Ising spin model with fields has $\Sigma = \mathbb{Z}_2$ and interaction lattice:



$$\sigma_i \in \Sigma$$

$$H = \sum_{i,j} J_{ij} \sigma_i \sigma_j + \sum_i v_i \sigma_i$$

Spin system simulation

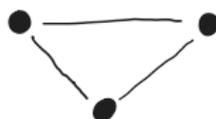
Every spin system can be simulated on a 2D Ising one [De16].

$$\Sigma = \mathbb{Z}_2$$

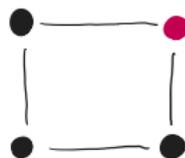
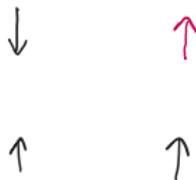
Configurations
 Σ^3

Interactions
 $\Sigma^3 \rightarrow \mathbb{R}$

Generic



Ising



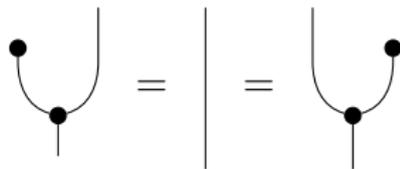
$$\Sigma^4$$

$$\Sigma^4 \rightarrow \mathbb{R}$$

The set-up (simulators)

Ambient category

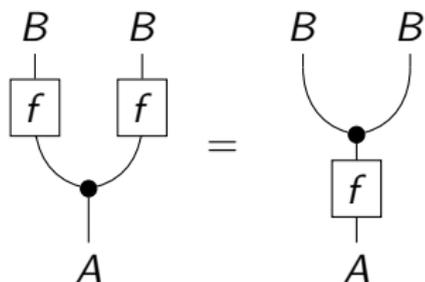
\mathcal{A} is **gs-monoidal**, an SMC with $A \rightarrow A \otimes A$ and $A \rightarrow I$ such that



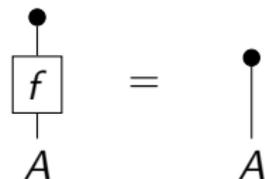
Key examples: Rel , Set , Rel_{poly} , $\text{Comp}(\mathbb{N})$, $\text{Poly}(\mathbb{N})$

Deterministic

functional morphism:



total morphism:

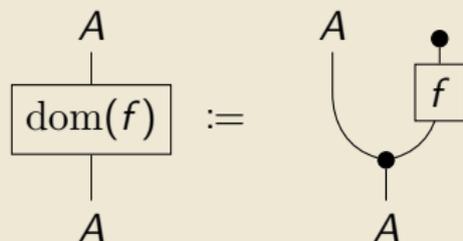


Functional + total = **deterministic**

Domain

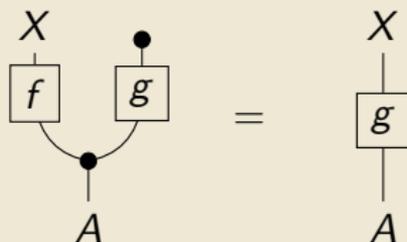
Definition ([Fr22])

The **domain** of $f: A \rightarrow X$ is



Definition

f agrees with g on the domain of g , denoted $f \sqsupseteq g$, if



Target–context category

Definition

A **target–context category** $(\mathcal{A}, T, C, \triangleright)$ is a gs-monoidal category \mathcal{A} with distinguished objects T and C , and preorders \triangleright on every $\mathcal{A}(A, T \otimes C)$, such that:

$$\triangleright f \sqsupseteq f$$

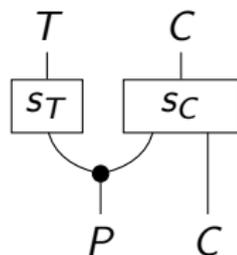
$$\triangleright f \sqsupseteq g \implies f \triangleright g$$

$$\triangleright f \triangleright g \implies f \circ h \triangleright g \circ h$$

for all $f, g: A \rightarrow T \otimes C$ and $h: Z \rightarrow A$.

\mathcal{A}	ambient cat.	$\text{Comp}(\mathbb{N})$	Rel_{poly}
A	object	\mathbb{N}^n for $n \in \mathbb{N}$	“sized” sets
f	morphism	computable fun.	bounded relations
T	targets	Turing machines	spin systems
C	contexts	input strings	spin configurations
\triangleright	ambient rel.	computation	energy condition

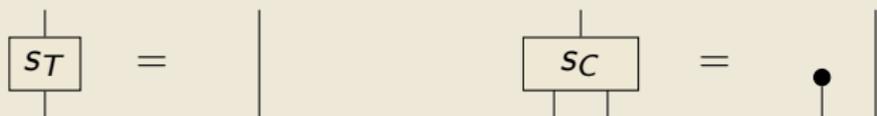
A simulator



$$P \in \mathcal{A}$$
$$s_T: P \rightarrow T$$
$$s_C: P \otimes C \rightarrow C$$

programs
compiler
context reduction

Example (trivial simulator)



Example (singleton simulator for TM)

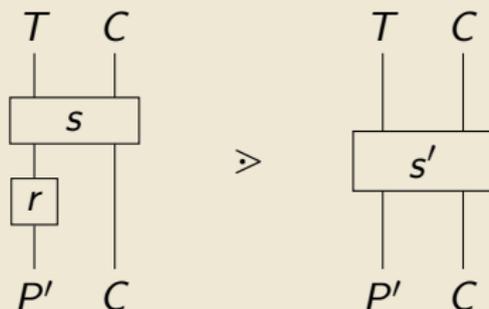


Universality

Reductions and universality

Definition

A **lax reduction** $r^* : s \rightarrow s'$ from simulator s to s' is a functional $r : P' \rightarrow P$ such that



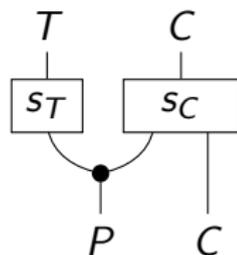
Definition

Simulator s is **universal** if there is a lax reduction $s \rightarrow \text{id}$ to the trivial simulator.

Examples (universal simulators)

- ▷ Trivial simulator
- ▷ Singleton simulator for a universal TM
- ▷ 2D Ising spin model with fields
- ▷ NP-complete language
- ▷ Dense subset (e.g. $T = \mathbb{R} \times \mathbb{R}_+$, $P = \mathbb{Q} \times \mathbb{R}_+$)
- ▷ A generating set ($T =$ tuples, $C =$ formulas)
- ▷ Weak limit ($T =$ cones, $\succ =$ cone factorization, $P = C = I$)
- ▷ Cofinal subset P of a poset (T, \succ) .

No-go theorem



$$\begin{array}{l} T \\ s_T: P \hookrightarrow T \\ s_C: P \otimes C \rightarrow C \end{array} \quad \begin{array}{l} \text{spin systems} \\ \text{2D Ising} \\ \text{config. embedding} \end{array}$$

Theorem

For a “suitably \succ -monotone” function $\varphi: T \rightarrow \mathbb{R}$, we have

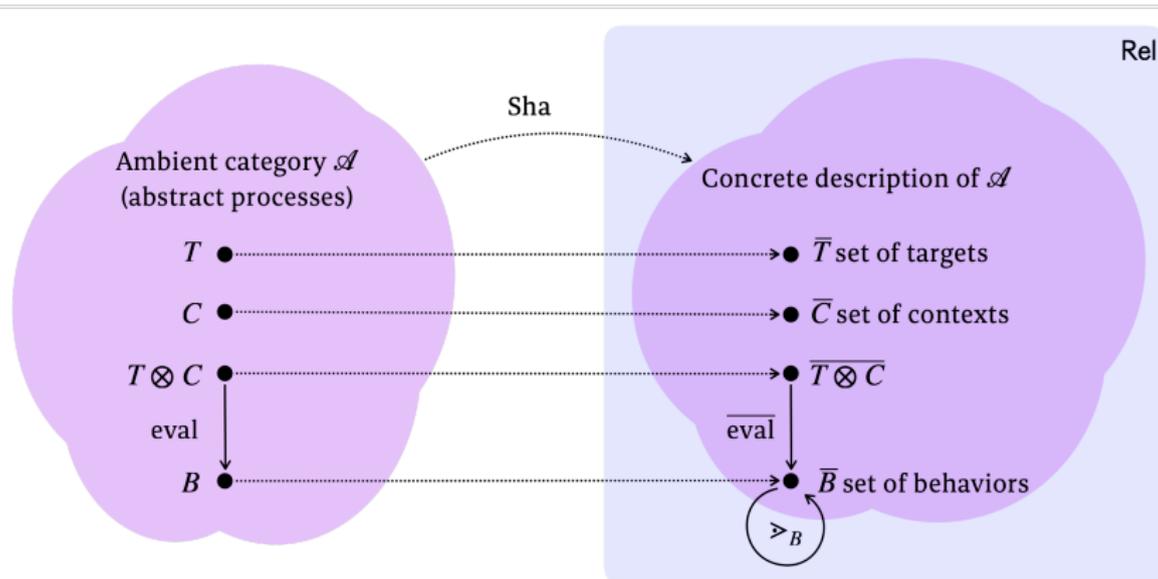
$$s \succ \text{id}_{T \otimes C} \implies \sup \varphi(\text{im}(s_T)) \geq \sup \varphi(T).$$

For spin systems, $\varphi = |\text{spec}|$ works, and RHS is ∞ , so

a universal spin model cannot be finite.

Relation to undecidability

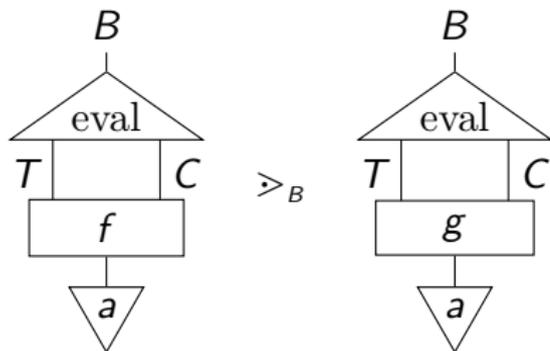
Intrinsic behavior structure



Intrinsic behavior structure

T	targets	TMs	spin systems
C	contexts	inputs	spin configurations
B	behaviors	outputs	energies + ...
\succ_B	preorder	=	...
eval	$T \otimes C \rightarrow B$	evaluation	measurement

$f \succ g :$



for all $a \in \mathcal{A}_{\text{det}}(I, A)$, such that RHS is defined.

Unreachability from universality

$F: P \otimes C \rightarrow B$ is a **complete parametrization** (CP) if for every f

$$\exists p_f \in \mathcal{A}_{\text{det}}(I, P) :$$

The diagrammatic equation shows two circuit diagrams connected by a greater-than symbol with a subscript B. The left diagram consists of a box labeled 'F' with an input 'C' on the right and an output 'B' on the top. A triangle labeled 'p_f' is connected to the bottom of the 'F' box, with its top vertex pointing towards the box. The right diagram consists of a box labeled 'f' with an input 'C' on the bottom and an output 'B' on the top.

A simulator s has **unreachability** if $\text{eval} \circ s$ is not a CP.

Theorem (Fixed Point Theorem à la [La69])

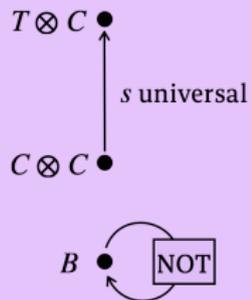
If $F: C \times C \rightarrow B$ is a CP, then every $g: B \rightarrow B$ has a (quasi) fixed point.

Lemma

If eval is a CP and s is universal, then $\text{eval} \circ s$ is a CP.

universal s + fixed-point-free $g \implies$ unreachability of id

Unreachability from universality



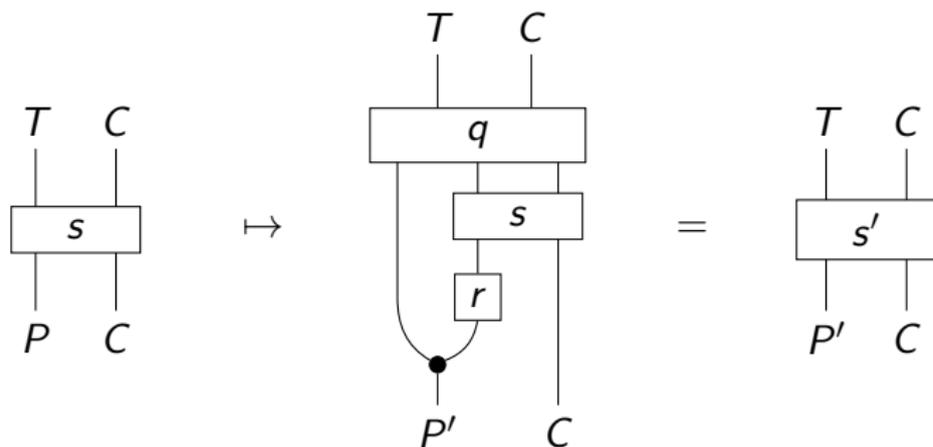
\Rightarrow

Morphisms $f: C \rightarrow B$

A diagram showing the space of morphisms $f: C \rightarrow B$. It consists of a large purple oval. Inside this oval is a smaller, darker purple oval with a dotted border, labeled "reachable". Below the "reachable" label is the text "eval(t, _) : C → B". To the right of the "reachable" region is the text "unreachable".

Hierarchy of universal simulators

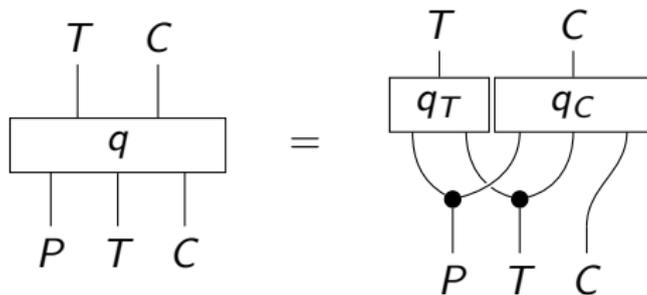
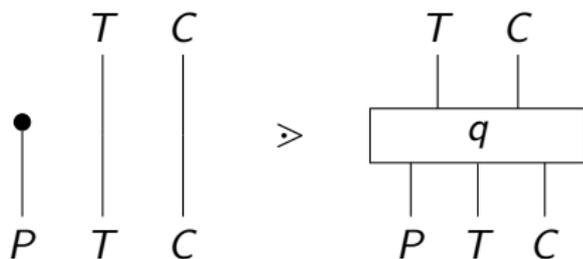
Simulator morphisms



r is deterministic ensures sequential composition

We also require that $(s' \text{ is universal}) \implies (s \text{ is universal})$.

Processings



Parsimony of simulators

Definition

s' is a **more parsimonious** simulator than s , written $s' \geq s$, if there exists a morphism $s \rightarrow s'$.

Theorem

The singleton simulator s_u for a universal TM is strictly more parsimonious than the trivial simulator.

- ▷ $s_u \geq \text{id}$ constructs right-inverse to the reduction.
- ▷ $s_u \not\leq \text{id}$ because $\exists t, t' : I \rightarrow T$ such that
 - ▷ t cannot simulate t' and
 - ▷ they both compile to $u \in T$

Summary

- ▷ Abstract notion of universality with several instances
- ▷ Necessary conditions for universality
- ▷ Morphisms of simulators \rightarrow non-trivial universality
- ▷ Fixed Point Theorem and unreachability
- ▷ target-context functors & simulator categories